

IMPACT MODELING

Sims (1980): Vector Auto Regression model.

Reasons for Impact Analysis

1. Structural Relationship (mainly concerned with sign, magnitude, significance of structural parameters)
2. Forecasting Future path (Forecast & forecast evaluation) of the economy
3. Policy Analysis (Policy scenarios) Play with policy scenarios

How VAR model is different from Regression equation

1. VAR is atheoretical (no economic theory needed)
2. It considers all variables in the system as endogenous variables and their lags as explanatory variables
3. The model studies dynamic interaction that exist b/w micro-economic variables

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a) theory

b) Static nature of the model

c) issue of endogeneity and

d) issue of identification

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$$w_t = (y_t, x_t, z_t)$$

1. Integration
2. Co-integration

If $w_t \sim I(0) \rightarrow$ LEVEL VAR

$$w_t \sim I(1)$$

and no

co-integration $\rightarrow$ DIFFERENCED VAR

$w_t \sim I(1)$ and C.I. $\rightarrow$ VECM.

C.I. - VAR

Reduced Form VAR

Reduced form Recursive VAR

Under both Level VAR and Differenced VAR we can have two models

- (a) Reduced Form VAR
- (b) Recursive VAR

SIMS (1980) - VAR MODEL.

$w_t = (x_t, y_t, z_t)$ — all these are observed

$w_t = (y_{1t}, y_{2t}, \dots, y_{nt})$
observed

if the DGP of w_t
VECTOR VECTOR VECTOR
↓ ↓ ↓
 $w_t = \mu_t + \chi_t$ — (4)
↑ ↑
Deterministic component Stochastic.

$$\mu_t = \mu_0 + \mu_1 t \quad (1)$$

if $\mu_1 = 0$ then $\mu_t = \mu_0$ (then there is no role of trend)

when write X in form of
VAR (p)

$$X_t = A_1 X_{t-1} + A_2 X_{t-2} + \dots + A_p X_{t-p} + e_t$$

$$X_t - A_1 X_{t-1} - A_2 X_{t-2} - \dots - A_p X_{t-p} = e_t$$

Identity matrix

$$\left[I_k - A_1(L) - A_2(L^2) - \dots - A_p(L^p) \right] X_t = e_t$$

NOTATION OF LAG

$$y_t = \alpha_1 y_{t-1} + \alpha_2 y_{t-2} + \dots$$

$$= \alpha_1 (L^1) + \alpha_2 (L^2) + \alpha_3 (L^3) + \dots$$

$$\dots + \alpha_p (L^p)$$

$$I_k - A_1 L - A_2 (L^2) - \dots$$

$$A_p(L^p) = A(L)$$

$$A(L) X_t = e_t \quad (2)$$

$$A(L)(w_t) = A(L)u_t$$

$$+ A(L) X_t$$

This is multiply $A(L)$ on both sides of 1

$$A(L) w_t = A(L) u_t + e_t$$

w_t has taken over the dynamics.
 $e_t = A(L) X_t$

$$[I_k - A_1(L) - A_2(L^2) - \dots]$$

$$A_p(L^p)] w_t = A(L) u_t + e_t$$

$$w_t = A_1 w_{t-1} + A_2 w_{t-2} + \dots$$

$$A_p w_{t-p} = A(L) u_t + e_t$$

$$w_t = A_1 w_{t-1} + A_2 w_{t-2} + \dots$$

$$u_t = u_0 + u_{1,t}$$

$$\dots + A_p w_{t-p} + A(L) u_t + e_t$$

$$A(L)[u_0 + u_{1,t}]$$

$$= A(L)u_0 + A(L)u_{1,t}$$

This portion is left

$$V_0 = [I_k - \sum_{j=1}^p A_j] u_0 + \left(\sum_{j=1}^p A_j \right) u_0$$

V_0 is represented by $A(L) u_0$. and $A(L) u_{1,t}$ is represented by V_1

$A(L)u_t$

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$$y_t = \left[I_k - \sum_{j=1}^p A_j \right] u_t$$

$$w_t = v_0 + v_1 + A_1 w_{t-1} + A_2 w_{t-2} + \dots + A_p w_{t-p} + \epsilon_t \quad (4)$$

Reduced form of
VAR

$$A(L)w_t = A(L)u_t + A(L)x_t$$

This corresponds to the DGP
of the model at the start

The w_t EQVA. CAN BE EXPRESSED

$$\begin{pmatrix} x_t \\ y_t \\ z_t \end{pmatrix} = \begin{pmatrix} v_{01} \\ v_{02} \\ v_{03} \end{pmatrix} + v_1 +$$

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$$\begin{pmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \\ A_{31} & A_{32} & A_{33} \end{pmatrix} \begin{pmatrix} x_{t-1} \\ y_{t-1} \\ z_{t-1} \end{pmatrix} + \dots$$

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$$\begin{pmatrix} A_{11} & A_{12} & A_{1p} \\ A_{21} & A_{22} & A_{2p} \\ A_{m1} & A_{m2} & A_{mp} \end{pmatrix}$$

$$\begin{pmatrix} x_{t-p} \\ y_{t-p} \\ z_{t-p} \end{pmatrix}$$

$$+ \begin{pmatrix} e_{t1} \\ e_{t2} \\ e_{t3} \end{pmatrix}$$

EXPANSION (LEVEL REDUCED VAR)

$$x_t = v_{01} + v_{1t} + A_{11} x_{t-1} + A_{12} y_{t-1} + A_{13} z_{t-1} + \dots + A_{11} x_{t-p} + A_{12} y_{t-p} + A_{1p} z_{t-p} + e_{t1}$$

$$y_t = v_{01} + v_{1t} + A_{21} x_{t-1} + A_{22} y_{t-1} + A_{23} z_{t-1} + \dots + A_{21} x_{t-p} + A_{22} y_{t-p} + A_{2p} z_{t-p} + e_{t2}$$

$$z_t = v_{03} + v_{1t} + A_{31} x_{t-1} + A_{32} y_{t-1} + A_{33} z_{t-1} + \dots + A_{31} x_{t-p} + A_{32} y_{t-p} + A_{3p} z_{t-p} + e_{t3}$$

$$A(1) w_t = v_0 + v_1 t + e_t$$

$$A(1) \overset{x \text{ eq.}}{y_t} w_t = v_{01} + v_{1t} + e_{1t}$$

$$A(1) \overset{y \text{ eq.}}{x_t} w_t = v_{02} + v_{1t} + y_t + e_{2t}$$

$$A(1) \overset{z \text{ eq.}}{x_t} w_t = v_{03} + v_{1t} + y_t + x_t + e_{3t}$$

$$A(L) = I_k - A_1(L) - A_2(L^2) - \dots - A_p(L^p)$$

$$= \cancel{I_k} - A_1(L) - A_2(L^2) - \dots - A_p(L^p)$$

Recursive LEVEL VAR

we run this model only if $w_t \sim I(0)$

$$x_t \sim I(0)$$

$$y_t \sim I(0)$$

$$z_t \sim I(0)$$

(This is redefined so that we don't come up with I_k)

classmate remodelled for consistency ☐

Ex.

$$y_t = \alpha_1 y_{t-1} + \alpha_2 y_{t-2} + \dots + \alpha_p y_{t-p} \quad \text{--- AR}(p)$$

$$y_t - \alpha_1 y_{t-1} - \alpha_2 y_{t-2} - \dots - \alpha_p y_{t-p} = e_t$$

$$[I_k - \alpha(L) - \alpha_2(L^2) - \dots - \alpha_p(L^p)] = \alpha(L)$$

So, the whole model

$$\alpha(L) \overset{\text{vector}}{y_t} = e_t \quad \text{--- AR}(p)$$